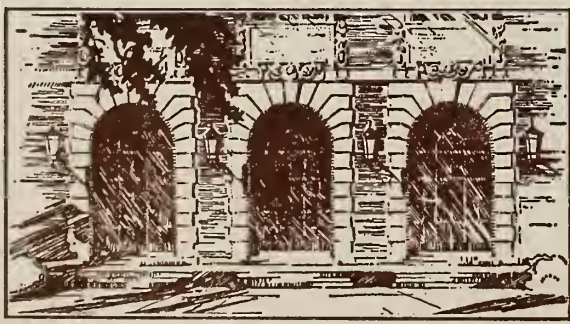


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A NOTE ON THE NON-EXISTENCE OF MULTIVALUE
A-STABLE METHODS OF ORDER GREATER THAN TWO

by

C. W. Gear

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A NOTE ON THE NON-EXISTENCE OF MULTIVALUE
A-STABLE METHODS OF ORDER GREATER THAN TWO*

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DEPARTMENT OF COMPUTER SCIENCE
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URBANA, ILLINOIS 61801

* Supported in part by contract US AEC AT(11-1)1469.

ABSTRACT

It is shown that the Dahlquist result limiting the order of A-stable multistep methods also applies to multivalued methods.

INTRODUCTION

In 1956, Dahlquist [1] showed that the maximum order of a strongly stable k-step linear multistep method is $k+1$. In 1963, he showed [2] that the maximum order of an A-stable multistep method is two. In 1966, the author [3] showed that an extension of multistep methods, called multivalued methods, led to a larger class of methods, called modified k-step methods, such that the order of a stable method could be increased to $2k$. Since then, the question of whether a multivalued method of order greater than two could be A-stable has remained. The answer is no and is shown by reducing the problem to the problem studied by Dahlquist.

PROOF OF RESULT

Consider the test equation $y' - \lambda y = 0$. Let $\underline{a} = [a_0, a_1, \dots, a_k]^T = [y, hy', \dots, h^k y^{(k)}/k!]^T$ be the data saved in the normal form of a multivalued method, and let $F(\underline{a}) = \delta_{-1}^T \underline{a} - \mu \delta_0^T \underline{a} = a_1 - \mu a_0$ where $\mu = h\lambda$. Then, from equation (11.21) in reference [4], the multivalued method is

$$\begin{aligned}
 \underline{a}_n &= A \underline{a}_{n-1} - \underline{\ell} \left[\frac{\partial F}{\partial \underline{a}} \underline{\ell} \right]^{-1} F(A \underline{a}_{n-1}) \\
 &= A \underline{a}_{n-1} - \underline{\ell} \left[\underline{\delta}_1^T \underline{\ell} - \mu \underline{\delta}_0^T \underline{\ell} \right]^{-1} (\underline{\delta}_1^T - \mu \underline{\delta}_0^T) A \underline{a}_{n-1} \\
 &= \left[I - \frac{\underline{\ell} (\underline{\delta}_1^T - \mu \underline{\delta}_0^T)}{\underline{\ell}_1 - \mu \ell_0} \right] A \underline{a}_{n-1} \\
 &= S \underline{a}_{n-1}
 \end{aligned}$$

where $\underline{\ell} = [\ell_0, \ell_1, \dots]^T$.

If the method is A-stable, then $\underline{a}_n = S^n \underline{a}_0 \rightarrow 0$ as $n \rightarrow \infty$ for fixed h whenever $\text{Re}(\mu) < 0$. Hence, A-stability implies that all eigenvalues of S are inside the unit circle when $\text{Re}(\mu) < 0$.

The eigenvalues of S are the same as the eigenvalues of

$$A \left[I - \frac{\underline{\ell} (\underline{\delta}_1^T - \mu \underline{\delta}_0^T)}{\underline{\ell}_1 - \mu \ell_0} \right]$$

Let $A - \xi I = [\underline{c}_0, \underline{c}_1, \dots, \underline{c}_k]$ where \underline{c}_i is the i -th column of $A - \xi I$, and let $A \underline{\ell} = \underline{v}$. Then we want to study the solutions of

$$\begin{aligned}
 0 &= \det \left[A - \underline{v} \frac{\underline{\delta}_1^T - \mu \underline{\delta}_0^T}{\underline{\ell}_1 - \mu \ell_0} - \xi I \right] \\
 &= \det \left[\underline{c}_0 + \underline{v} \frac{\mu}{\underline{\ell}_1 - \mu \ell_0}, \underline{c}_1 - \underline{v} \frac{1}{\underline{\ell}_1 - \mu \ell_0}, \underline{c}_2, \dots, \underline{c}_k \right] \\
 &= \det [\underline{c}_0, \underline{c}_1, \underline{c}_2, \dots, \underline{c}_k] \\
 &\quad + \det \left[\underline{v} \frac{\mu}{\underline{\ell}_1 - \mu \ell_0}, \underline{c}_1, \underline{c}_2, \dots, \underline{c}_k \right] \\
 &\quad - \det \left[\underline{c}_0, \underline{v} \frac{1}{\underline{\ell}_1 - \mu \ell_0}, \underline{c}_2, \dots, \underline{c}_k \right]
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{1}{\ell_1 - \mu \ell_0} \left[\ell_1 \{ \det(A - \xi I) - \det[c_0, \frac{v}{\ell_1}, c_2, \dots, c_k] \} \right. \\
 &\quad \left. - \mu \ell_0 \{ \det(A - \xi I) - \det[\frac{v}{\ell_0}, c_1, c_2, \dots, c_k] \} \right] \\
 &= \frac{1}{\ell_1 - \mu \ell_0} [\rho(\xi) - \mu \sigma(\xi)] \tag{1}
 \end{aligned}$$

where $\rho(\xi)$ and $\sigma(\xi)$ are the weighted sums of some determinants which are polynomials in ξ and independent of μ . Now this is the same as the polynomial that determines the roots of the constant coefficient difference equation arising when a linear multistep method is applied to $y' = \lambda y$. If the method has order p , then one eigenvalue of S , namely one zero of (1) must approximate e^μ to order p , and this is the necessary and sufficient condition for ρ and σ to determine a p -th order multistep method. If the eigenvalues of S are less than one for all $\text{Re}(\mu) < 0$, then the corresponding multistep method is A-stable, but this is not possible if $p > 2$.

LIST OF REFERENCES

- [1] Dahlquist, G., "Numerical Integration of Ordinary Differential Equations," Math. Scandinavica, 4, (1956) pp. 33-50.
- [2] Dahlquist, G., "A Special Stability Problem for Linear Multistep Methods," BIT, 3 (1963) pp. 27-43.
- [3] Gear, C. W., "The Numerical Integration of Ordinary Differential Equations of Various Orders," Argonne National Lab Report #ANL 7126, Argonne, Illinois (1966).
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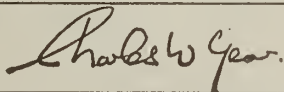
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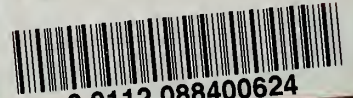
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